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NAVAL POSTGRADUATE SCHOOL Monterey, California



WHOLESALE PROVISIONING MODELS: MODEL OPTIMIZATION

by

G. T. Howard

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Commanding Officer Fleet Material Support Office Mechanicsburg, PA 17055

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NAVAL POSTGRADUATE SCHOOL Monterey, California

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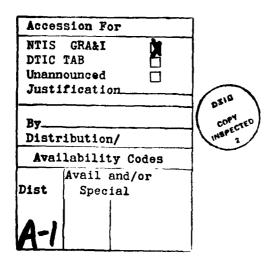
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Abstract

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I. Introduction

A. Overview

The purpose of this report is to discuss solution methods for several problems arising in inventory provisioning. Two related types of problems are considered:

- optimization of a performance measure subject to a budget constraint
- 2) minimization of cost subject to a constraint on performance. The performance measures considered are Supply Material Availability (SMA), Mean Supply Response Time (MSRT), and "Pseudo-Availability" (PA). The basic approach to these problems is dynamic programming.

First the problems are formulated and solved using one recursive technique. Then a more efficient recursion is presented and discussed in the context of maximizing MSRT subject to a budget constraint.

These same budget constrained problems are formulated, discussed and solved using a marginal analysis approach in [2] and [3]. That method, although fast, does not guarantee that optimal solutions are obtained. This report provides a method of obtaining optimal solutions and thus provides a means of evaluating heuristic methods. In addition, this report shows how the performance constrained budget minimization problems can be solved directly. By contrast, reference [2] addresses this problem using generalized Lagrange Multipliers or by solving the budget constrained performance problem repeatedly for various budget levels.

The second recursion presented here is considerably faster than the first and it also guarantees an optimal solution in some cases. It is competitive in speed with the marginal analysis method for small and medium-sized

problems, but it is inefficient for problems with a large number of items or large budget values. Its virtue lies in its ability to get exact solutions to medium-sized problems.

B. Problem Formulations, budget constrained

This report considers three specific budget constrained optimization problems arising in inventory provisioning. These problems are formulated and discussed in detail elsewhere [2] and will be stated here without extensive explanation.

Following [2] we let

n = the total number of items considered for provisioning

C; = the unit cost of item i

 E_4 = the essentiality code for item type i

 λ_i = the demand rate for item i

 T_i = the procurement leadtime for item i

S_i = the number of items of type i provided (the decision
 variables)

 $Z_{i}(S_{i})$ = the performance measure for item i when S_{i} units are stocked

 $D_{i}(S_{i}) = Z_{i}(S_{i+1}) - Z_{i}(S_{i})$

 $p_{i}(x_{i})$ = probability that demand for item i is x_{i} during the provisioning interval

 $P_{i}(x_{i})$ = cumulative probability of x_{i} or fewer demands during a provisioning interval

 $MTTR_{i}$ = mean time to repair or replace item i

 ${\rm MTBF}_{i} \ \ {\rm ^{*}\ mean\ time\ between\ failures\ ^{*}}\ 1/\lambda_{i}$

 ${\sf MSRT}_i({\sf S}_i)$ = mean supply response time when ${\sf S}_i$ units are stocked.

The three budget constrained problems considered are:

al) maximize Supply Material Availability (SMA), defined as

$$SMA(S_1,...,S_n) = \sum_{i=1}^{n} E_i \lambda_i T_i Z_i^{(1)}(S_i) / \sum_{i=1}^{n} E_i \lambda_i T_i$$

where

$$Z_{i}^{(1)}(S_{i}) = (1 - P_{i}(S_{i})) + (S_{i} - \lambda_{i} T_{i})(1 - P_{i}(S_{i}))/\lambda_{i} T_{i}$$

bl) minimize Mean Supply Response Time (MSRT), defined as

$$MSRT(S_1,...,S_n) = \sum_{i=1}^{n} E_i \lambda_i T_i Z_i^{(2)}(S_i) / \sum_{i=1}^{n} E_i \lambda_i T_i$$

where

$$Z_{i}^{(2)}(S_{i}) = (1 - P_{i}(S_{i}))(T_{i}/2 - S_{i}/\lambda_{i} + \frac{S_{i}(S_{i}+1)}{2\lambda_{i}^{2}T_{i}}) + P_{i}(S_{i})(\lambda_{i} T_{i} - S_{i})/2\lambda_{i}.$$

cl) maximize Pseudo-Availability (PA), defined as

$$PA(S_1,...,S_n) = \prod_{i=1}^{n} Z_i^{(3)}(S_i)$$

where

$$Z_{i}^{(3)}(S) = MTBF_{i}/(MTBF_{i} + MTTR_{i} + Z_{i}^{(2)}(S_{i}))$$
.

In each of the budget constrained problems above the objective is to be optimized by selection of S_1, \ldots, S_n subject to the constraints

$$\sum_{i=1}^{n} C_{i} S_{i} \leq B , \qquad S_{i} \geq 0 \text{ integer}$$

where B is the specified budget level.

C. Problem Formulations, Performance Constrained

In addition to the three problems just stated, we consider three related problems in which the cost is to be minimized subject to a constraint on performance.

a2) min
$$\sum_{i=1}^{n} C_{i} S_{i}$$
s.t.
$$SMA(S_{1},...,S_{n}) \geq SMA$$

$$S_{i} \geq 0 \text{ integer.}$$

b2) min
$$\sum_{i=1}^{n} C_{i} S_{i}$$
s.t. $MSRT(S_{1},...,S_{n}) \leq MSRT$

$$S_{i} \geq 0 \text{ integer.}$$

c2) min
$$\sum_{i=1}^{n} C_{i} S_{i}$$
s.t.
$$PA(S_{1},...,S_{n}) \ge PA$$

$$S_{i} \ge 0 \text{ integer.}$$

II. Solution Method and Examples

A. Dynamic Programming Approach

The computer program used to solve these problems is DP4, a general purpose program for performing dynamic programming tabular computations. Here we will describe the general nature of that program and those elements required to tailor it for use in the problems considered in this report.

The DP4 program deals with a problem consisting of n related stages each of which is characterized as shown in figure 1.

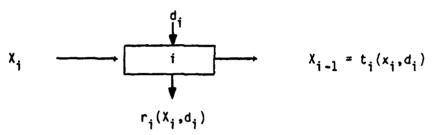


Figure 1. A single-stage decision problem.

In figure 1

 X_i is the "state" variable d_i is the decision variable r_i is the stage return function t_i is the stage transformation function.

In the overall problem consisting of n stages the output state variable from stage i, namely X_{i-1} , is the input to stage i-1. Thus, the n stage problem can be pictured as in figure 2.

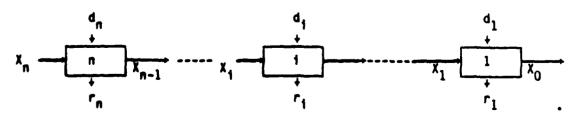


Figure 2. n-stage decision problem.

The state variable X_i can easily be understood in the context of the budget constrained problems as the amount of resource (money) remaining to be allocated to stages i, i-1,...,1. The stages, of course, correspond to the items in the inventory problems.

At each stage i a decision d_i must be made. The decision has two effects. First, it yields a return r_i , the performance measure associated with the current item. Second, it yields a value of X_{i-1} which serves as the input to the remainder of the decision process. The decision d_i must be made with consideration both for the immediate return r_i and the future state X_{i-1} . The overall problem is to make the series of decisions d_n, \ldots, d_1 to optimize some function of the individual stage returns.

In the problem (a1), where $\,S_{\,\dot{1}}\,$ is the decision variable, we can let the return functions be

$$r_{i}(X_{i}, S_{i}) = E_{i} \lambda_{i} T_{i} Z_{i}^{(1)}(S_{i}) / \sum_{i=1}^{n} E_{i} \lambda_{i} T_{i} \qquad i = 1,...,n$$

and the stage transformation functions be

$$X_n = B$$

$$X_{i-1} = t_i(X_i, S_i) = X_i - C_i S_i \qquad i = 1,...,n.$$

The overall return function is the sum of the individual return functions. Namely,

$$SMA(S_1,...,S_n) = \sum_{i=1}^{n} r_i(X_i, S_i)$$
.

The object remains to select S_1, \dots, S_n to optimize this return.

We let $f_i(X_i)$ = the optimal total return from stages i, i-1,...,l given that we enter stage i with state variable X_i . Then we can write the recursive equations for this optimization as

$$f_{i}(x_{i}) = \max_{S_{i}} \{r_{i}(X_{i}, s_{i}) + f_{i-1}(X_{i-1})\}$$

$$s.t. \quad X_{i-1} = X_{i} - C_{i} S_{i}$$
and
$$0 \le S_{i} \le X_{i}/C_{i}$$
and
$$S_{i} = integer$$

for i = 2, ..., n.

The equation at stage 1 is

$$f_1(X_1) = \max_{S_1} r_1(X_1, S_1)$$

s.t. $0 \le S_1 \le X_1/C_1$
and S_1 integer.

The program DP4 performs this optimization provided the user supplies the following subroutines and data.

Required subroutines

- 1. STGRET this subroutine defines the function $r_i(X_i, d_i)$
- 2. TRANFM defines the stage transformation function $t_i(X_i, d_i)$
- 3. DLIMIT defines the range of decision values d_i which can be considered for the particular value of X_i under consideration
- 4. STORE allows the input of constants to be used in the other subroutines.

Required Data

1. n - the number of stages

2. For each stage i

XLOW - the lowest value of X_i to consider

XHIGH - the highest value of X_i to consider

DELX - the increment for X_i

XMODE - tells whether to maximize or minimize

XSTAGE - tells how this stage return relates to lower numbered stage returns (sum, product).

The methodology is essentially the same for the performance constrained problems. There the return functions $r_i(X_i, d_i) = c_i d_i$. The state variable X_i is interpreted as the portion of the performance measure to be attributed to stages 1,...,i. The stage transformation functions in problem (a2) and (b2) are

$$X_{i-1} = X_i - Z_i(S_i)$$
.

In problem (c2) the stage transformation is

$$X_{i-1} = X_i/Z^{(3)}(S_i)$$
.

The program DP4 and the subroutines are shown in Appendix A. The subroutines are written to solve any of the problems (a1), (b1), (c1) or (a2), (b2), (c2). Thus they involve complications not needed for solving just one of these problems.

B. Examples

Several example problems were solved to illustrate the approach discussed here. All of the problems involved $n \approx 10$ items and all used the data shown in table 1.

Data

n	λ	Time	Cost	MTTR	E
1	5.0	1.0	1.0	.0137	1.0
2	2.0	1.0	2.0	.0274	1.0
3	3.0	1.0	5.0	.0137	1.0
4	5.0	1.0	10.0	.0822	1.0
5	10.0	1.0	20.0	.0274	1.0
6	25.0	1.0	5.0	.0027	1.0
7	1.0	1.ŭ	1.0	.0054	1.0
8	1.0	1.0	100.0	.0411	3.0
9	0.5	1.0	50.0	.0082	1.0
10	2.0	1.0	10.0	.1370	3.0

Table 1: Data for Examples

1. The budget constrained problems.

Tables 2, 3, and 4 summarize the solutions for the example problems (a1), (b1), and (c1). These are the budget constrained problems.

B = Budget = max SMA =	300 .750654	295 .746466	290 .741160	285 .736563	280 .732964
decision S ₁ =	4	4	4	4	4.
s ₂ =	4	4	4	4	4
S ₃ =	4	4	4	4	4
S ₄ =	5	5	5	4	5
S ₅ =	2	2	2	2	1
S ₆ *	29	28	27	28	29
s ₇ =	3	3	.3	3	3
s ₈ =	O	O	0	0	0
s ₉ =	0	0	0	0	0
s ₁₀ =	3	3	3	3	3

Table 2: Solutions to example problem (al)

B = min MSRT =	300 .0838231	295 .0859625	290 .0878466	285 .0900560	280 .0927486
decision S_1	2	2	2	2	2
s ₂	3	3	3	3	3
s ₃	3	4	3	3	3
s ₄	4	4	4	4	4
s ₅	5	4	4	4	4
s ₆	21	23	23	22	21
s ₇	2	2	2	2	2
s ₈	0	0	0	υ	0
· S ₉	0	0	0	0	0
s ₁₀	3	3	3	3	3

Table 3. Solutions to example problem (b1)

8 = max PA =	300 .0403727	295 .0387421	290 .037005	285 .0355446	280 .0341911
decision S_1	3	3	3	3	3
s ₂	4	4	4	4	4
s ₃	5	4	5	5	5
S ₄	5	5	5	5	5
S ₅	3	3	2	2	2
S ₆	26	26	26	27	26
S ₇	4	4	4	4	4
s ₈	0	0	0	v	0
S ₉	O	0	0	0	0
s ₁₀	2	2	3	2	2

Table 4. Solutions to example problem (c1)

2. The performance constrained problems.

The related performance constrained problems were also solved for illustration. For example, the problem (a2) was solved using the data from Table 1 with the restriction that SMA \geq .732964. The solution to that problem is the same as the solution shown in the last column of Table 2 since the value .732964 is the (largest) value of SMA corresponding to a budget of 280.

III. Modifications to Basic Method

A. An Alternative Recursion

An alternative and more efficient approach is available for the budget constrained problems.

The approach is based on a different recursion from that used in Section 2 and is very similar to an approach used to solve the "cargo loading problem". See for example Dreyfus [1].

The cargo loading problem, stated as a maximization, is:

$$\max \sum_{j=1}^{N} v_j d_j$$
s.t.
$$\sum_{j} c_j d_j \leq B$$

$$d_j \geq 0 \text{ integer .}$$

Although many methods are available for solving this problem, the one of interest to us is based on the following recursion

$$f(b) = \max_{j \in \{1,...,N\}} \{v_j + f(b-c_j)\}$$

where f(b) is the optimal total return that can be obtained when a budget of b is available.

To illustrate this method consider the data in Table 5.

Table 5. Data for example using alternative recursion

The computation proceeds with increasing values of b until b = B is reached. The process can be viewed as shown in figure 3 where a template

representing the available items is placed over the budget value of current interest. The template points back to previously determined optimal solution. Each of these previous solution is considered for updating by including one more item of the type inducted by the template. The updated solutions are compared and the best selected as the solution for the current value of b. The illustration shows the template at the budget value of 7. The optimal solutions for b = 0,1,...,6 have already been computed. The comparison at b = 7 is among the solution at 6 with an additional item 1 for a total return of 9, the solution at 4 with an additional item of type 2 for a total return of 10, and the solution at 3 with an additional item of type 3 for a return of 10. Either of the last two is chosen and recorded as an optimal solution

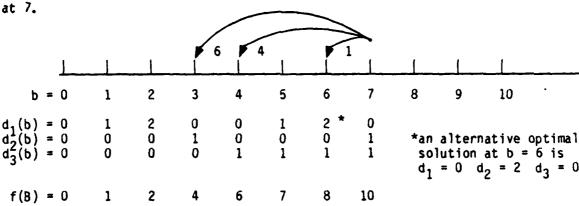


Figure 3: Illustration of solution method using the alternative recursion.

A very simple modification of this procedure can be used to solve the problems of the type discussed in this report. We consider

$$\max \sum_{j=1}^{n} r_{j}(d_{j})$$
s.t.
$$\sum_{j=1}^{n} c_{j} \cdot d_{j} \leq B$$

$$d_{j} \geq 0 \text{ integer}$$

where the return functions $r_j(d_j)$ are concave. The procedure below is not guaranteed to give the optimal solution for all $r_j(d_j)$ but is guaranteed if the $r_j(d_j)$ are points on a concave function.

In this case we will represent the return functions $\ r_j(d_j)$ as the sum of the marginal values of additional items of type $\ j$.

$$r_{j}(d) = + \sum_{i=1}^{d} m_{j}(i)$$

Thus $r_j(2) = m_j(0) + m_j(1) + m_j(2)$. These marginal values form a sequence with the properties that

$$m_j(i) > 0$$

and

$$m_{j}(i) > m_{j}(k)$$
 $i < k$.

The same algorithm as before was applied with the modification that the value term \mathbf{v}_j , which was formerly constant, is replaced by $\mathbf{m}_j(i)$ for the appropriate value of i. The program which implements this algorithm was called RECUR.

It should be noted that the discussion above treats the constraint as an inequality, but the function f(b) in this section is computed for the constraint

$$\sum_{j=1}^{N} c_{j} x_{j} = b.$$

For this reason we may have in a maximization problem

$$f(b_1) > f(b_2)$$

although $b_1 < b_2$. That is, if we require the equality to be met exactly, it is not necessarily true that a larger budget is better. The program prints the values of f(b) for several values of b so the optimal value of $b \le B$ can be found visually.

B. Minimum Orders

1) RECMOD

A modification was made to the program RECUR to permit the user to specify minimum packaging quantities of each item. That is, item i is assumed to be packaged with q_i items per package. The provisioning can select only whole packages of each item. This modification resulted in the program RECMOD given in the Appendix.

2) Example

To illustrate the RECMOD program, consider the example problem (a2) solved previously. The optimal solution for budget B = 300 is repeated in Table 2 for the case in which all $q_i = 1$.

n	1	2	3	4	5	6	7	8	9	10	Objective
qi	1	1	1	1	1	1	1	1	1	1	
di	2	3	3	4	5	21	2	0	0	3	.0838231
qi	2	1	1	5	1	1	1	3	1	1	
di	2	3	3	5	4	23	2	0	0	3	.0847410

Table 6. Solution to Example using RECMOD.

The optimal solution is also shown for a modified problem in which not all $\,q_{\,i}^{}$ are equal to $\,1$.

C. Discussion

The modified recursion just discussed has been implemented for the problem (a2) which is to minimize MSRT subject to a budget constraint. The method can also be applied to the other budget constrained problems, but this has not yet been done. All that is required is to modify the program to compute SMA or PA instead of MSRT and to maximize instead of minimize.

There is a difficulty in extending this method to problems in which the item costs are arbitrary values. The method is very effective when the costs are all integer and can be scaled so that the smallest cost is 1. If arbitrary costs are allowed, the algorithm can become ineffective for all except small values of B. Consider for example the costs of \$1.00, \$1.21, \$1.27 for three items. Let the budget be \$25.00. The problem could be solved by scaling the costs to be 100, 120, and 125 and the budget to be 2500, but then too many values of b must be considered when many of them are not possible. Alternatively the algorithm can step to the "next possible value" and will consider the following sequence of values b = 100, 121, 127, 200, 221, 227, 242, 248, 254, 300, 321, 327,....

As the process continues, depending on the relative values of the costs, the sequence becomes more dense and may eventually include all possible values of b. This is ineffective and cumbersome for large values of B.

It is also not possible to apply the modified recursion for the performance constrained problems. On the other hand, the budget constrained problems are solved very rapidly and the relationship between cost and performance can easily be determined from solving the budget constrained problem using the first recursion. In fact, if MSRT is minimized for a budget of B, the solution is actually obtained for all values of b up to and including B. Those results reveal the relationship between performance and budget.

APPENDIX-PROGRAM LISTINGS

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53 - 55	COL 55	4 ODE S	*	I	IF THE FIBONACCI SEARCH IS TO BE USED
•			. =	Z	IF THE FIBONACCI SEARCH IS

NAVAL POSTGRADUATE SCHOOL

FORTRAN

A1

DATA DESCRIPTION OF LAST CARD FOR PROBLEM
THE OPTIMUM DECISIONS ARE TO BE PRINTED OUT FOR A PROCESS WITH
NMAX STAGES, FURTHER, FN(XN) IS TO BE OPTIMIZED WITH RESPECT TO XN
WHEN THE PROGRAM COMPLETES THE REQUESTED PRINTOUT IT WILL RETURN
TO THE BEGINNING AND START A NEW PROBLEM IF THERE IS DATA, IF NO
DATA, IT WILL EXIT

COLUMNS	JUSTIFY	VARIBLE NAME	MEANING
1 - 15	ANY	XN1	AT STAJE NMAX, OPTIMIZE FN(XN) FCR XV NOT LESS THAN XVI
16 - 30	ANY	XN2	AT STAGE NMAX, OPTIMIZE FN(XN) FCR XN NOT GREATER THAN XN2

DESCRIPTION OF THE SUBROUTINE TRANSMITS THE MAIN PROGRAM TRANSMITS XN. DN. AND NUMBER (THE SEQUENCE NUMBER OF THE PROBLEM) TO THE SUBROUTINE AND THE SUBROUTINE CALCULATES YN (THE OUTPUT OF THE STAGE 1.6. YN=XN-1)

DESCRIPTION OF THE SUBROUTINE STORET THE MAIN PROGRAM TRANSMITS XN, DN, YN, AND NUMBER TO THE SUBROUTINE, AND THE SUBROUTINE CALCULATES RY (THE STAGE RETURN)

DESCRIPTION OF SUBROUTINE STORE
THE MAIN PROGRAM CALLS THE SUBROUTINE RIGHT AFTER READING THE
FIRST DATA CARD AND DEFINING NUMBER. THE PURPOSE OF THIS
SUBROUTINE IS TO ALLOW THE STORING OF CONSTANTS IN COMMON STORAGE
FOR THE POSSIBLE USE OF SUBROUTINES STORET AND TRANFM

DATA WHICH WILL BE READ FROM DATA CARDS AT OBJECT TIME BY
THE SUBROUTINE STORE MUST BE INSERTED BETWEEN THE FIRST DATA CARD
AND THE GROUP OF CARDS WHICH DESCRIBE THE INDIVIDUAL STAGES

C

```
DESCRIPTION OF SUBROUTINE DLIMIT
THE MAIN PROGRAM TRANSMITS N.XN. AND NUMBER TO THE SUBROUTINE,
AND THE SUBROUTINE CALCULATES DLOW, DHIGH, AND DELD
WHERE DLOW = LOWEST VALUE OF DN FOR THAT PARTICULAR VALUE OF N AND
                          DFIGH = HIGHEST VALUE OF DN FOR THAT PARTIC

AND XN

DELD = INCREMENT IN DN FOR THAT PARTICULAR

IF ANY OF THESE VARIBLES DO NOT CHANGE, THEY CAN

SUBROUTINE STORE AND NOT MENTIONED IN SUBROUTINE
                                                                                                                                                                                                      FOR THAT PARTICULAR VALUE OF N
                                                                                                                                                                                                                                                                                VALUE OF N AND XN BE SET IN OLIMIT
                          IF ANY SUBROUTINE SETS NUFF TO -1 THEN THE PROGRAM IGNORES THE VALUE OF DN BEING PROCESSED AT THAT NOMENT, AND IGNORES ALL LARGER VALUES OF DN FOR THAT PARTICULAR VALUE OF XN AT THAT PARTICULAR STAGE--THIS FEATURE IS DISABLED 4 HEN USING THE FIBONACCI SEARCH
THIS PROGRAM USES TAPES 3 AND 4 FOR SCRATCH

NSS2 ZERO FOR ENTIRE PROBLEM SOLVING AND OUTPUT

NSS2 NON-ZERO FOR OUTPUT FROM PREVIOUS PROBLEM

DIMENSION FN(10001), FNM1(10001), NOFXN(10001)

REAL * 8 HOLMIN', MOLOL), OLD ,

REAL * 8 TAB(4)

COMMON /CONTAB

COMMON XN,N, N, YN, RN, SLOW, XHIGH, DELX, DLOW, DHIGH, DELD, NUMBER

COMMON XN,N, N, YN, RN, SLOW, XHIGH, DELX, DLOW, DHIGH, DELD, NUMBER

COMMON YLOW, YHIGH, DELY, NUFF, FN, JIOP, NNFL AG, NM AX, XLAM

COMMON A, B, C, D, E, SUMELT, KODE1, KODE2

EQUIVALENCE (FN(1), FNM1(1), JNOFXN(1);

WRITE(6,1000) HOLMIN, HOLOLD, (TAB(I), I=1,4)

1000 FORM AT(1X, 6A6)

MAX=10001

INTAPE=7

NOUTPE=6

CALL SEARCH(0.0,0.0,-1.0,0.0,DN3EST,BEST)

NPAGE=0

NUMBER=0

240 READ(INTAPE,100,END=2000) NMAX, MTAPE, SOLVE
        240 READ (ÎNTAPE, 100, END=2000) NMAX, YTAPE, SOLVE
100 FORMAT(215, A5)
MTAP = MTAPE
NDIT TO=0
     NDIT TO=0
NCALC=4
IF(MTAPE-4; 405,501,405

501 NCALC=3
GO TO 172
405 IF(MTAPE) 322,322,172

322 MTAPE=3
172 NTAPE=MTAPE
REWIND MTAPE
NUMBER=NUMBER+1
CALL STORE WAS MOVED FROM HERE
IF(SOLVE-HOLDLD) 301,302,301

302 NSS2=1
NPAGE=NPAGE+1
WRITE(NOUTPE,152) NPAGE
152 FORM AT (1H1100X4HPAGE14)
WRITE(NOUTPE,303) MTAPE
303 FORMAT (58M THE TABLES OF FN(X)
1 APEI5,35H WILL BE USED TO SOLVE
READ (MTAPE) NMAX
REWIND MTAPE
GO TO 304

301 NSS2=0
CALL STORE
NPAGE=NPAGE+1
                                                                                                                                                              FN(XN) AND DN(XN) W
SOLVE THIS PROBLEY)
                                                                                                                                                                                                                                                       WHICH ARE ON LOGICAL T
```

301 NSS2=0
CALL STORE
NPAGE=NPAGE+1
HRITE(NOUTPE, 152) NPAGE
HRITE(NOUTPE, 305) MTAPE
305 FORMAT(89H THE COMPUTER IS TO CALCULATE TABLES OF FN(XN) AND DN(XN)

NAVAL POSTGRADUATE SCHOOL FILE: DP4 FORTRAN AL

```
FILE: DP4 FORTRAN AL NAVAL POSTGRADUATE SCHOOL

1 AND STONE THEM ON LOGICAL TAPEIS;

500 WRITE HIDE: NAMAX
304 WRITE HIDE: NAMAX
305 FORMAT LINE HIDE: NAMAX
306 FORMAT LINE HIDE: NAMAX
306 FORMAT LINE HIDE: NAMAX
307 WRITE NOUTE: 300 MAXX, MTAP, SILVE
2006 FORMAT LINES - 0.
2006 FORMAT LINES - 0.
2006 FORMAT LINES - 0.
2007 FORMAT LINES - 0.
2007 FORMAT LINES - 0.
2007 FORMAT LINES - 0.
2008 FORMAT LINES - 0.
2009 FORMAT LINES - 0.
```

```
1 IS TO MAXIMIZE THE MINIMUM RETURN)
GO TO 132
14 WRITE(NOUTPE, 19) NM1.N
19 FORMAT(40H THE COMPOSITION OPERATOR BETWEEN STAGESI6, 4H ANDI6, 34H
11S TO MINIMIZE THE MAXIMUM RETURN)
132 DO 136 I=1.ITOP
134 BEST=1.0E+35*XMODE
   134 BEST=1.0E+35*XMODE

X=I-1

XN=XLOW+X*DELX

NUFF=1

CALL DLIMIT

IF(MODES) 602,602,603

603 CALL SEARCH(DLOW, DHIGH, DELD, XMODE, DNB EST, BEST)

GO TO 400

602 KTOP=(DHIGH-DLOW)/DELD+1.001

223 DO 137 J=1,KTOP

X=J-1

DN=DLOW+X*DELD
 ÔN=DÊOW+X+DELD
Jump may be set to 1 in tranfm to indicate an inféasible XN-1
C
```

FILE: DP4 FORTRAN AL NAVAL POSTGRADUATE SCHOOL

```
YLOW=XLOW
YHIGH=XHIGH
DELY=DELX
JTOP=ITOP

123 CONTINUE
WRITE(NTAPE) (FN(II), II=1, ITOP)

161 END FILE MTAPE
197 REWIND MTAPE
READ (MTAPE) NMAX
N=NMAX
161 END FILE MTAPE
READ (MTAPE)
READ (MTAPE)
READ (MTAPE)
READ (MTAPE)
READ (MTAPE)

201 105 22 I=1

222 READ MTAPE)
407 READ MTAPE)
READ (MTAPE)

         183 BEST=FN(J)
JSAVE=J

182 CONTINUE
X=JSAVE-1
XM=XLGM+X*DELX
HRITE(NOUTPE,184) XN, BEST

184 FORMAT(12H OPTIMAL XN=1PE14.5.164
READ(MTAPE) (DNOFXN(II), II=1, IT)P)

186 ON=DNOFXN(JSAVE)
CALL TRANFM

204 WRITE(NOUTPE,188)
188 FORMAT(7HO N18X2HXN18X2HDN16X4NNN=0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                          OPTIMAL RETURN=1PE14.51
          188 FORMAT(7HO NI 8X2H XN1 8X2HDN16X4HXN-1
NN=0
203 WRITE(NOUTPE, 189) N, XN, DN, YN
189 FORMAT(17, 1P3E20. 5)
NN=NN+1
N=N-1
IF(N-1) 244, 193, 193
244 GO TO 240
193 DO 406 I=1.4
406 BACK SPACE MTAPE
READ(MTAPE) XLOW, XHIGH, DELX, ITOP, XMODE
READ(MTAPE) (DNOFXN(II), II=1, ITOP)
L=(YN-XLOW)/DELX+1.001
IF(L) 214,214,215
                                                                                                                                                                                                                                            N18x2HXN18x2HDN16x4HXN-1)
```

```
214 L=1
219 NP1=N+1
WRITE(NOUTPE,210) NP1,XN,DN,YN
NN=NN+7
215 IF(L-ITOP) 218,216,217
216 DN-DNDFXN(L)
XN=YN
GD TO 196
217 L=1TOP
GD TO 219
218 XN=YN
194 X=L-1
X=XLOW+X*DELX
DN-DNOFXN(L)+(DNOFXN(L+1)-DNOFXN(L))*(XN-X)/DELX
196 CALL TRANFM
1F(NN-50) 203,203,220
220 NPAGE=NPAGE+1
WRITE(NOUTPE,152) NPAGE
GD TO 204
112 WRITE(NOUTPE,113) MAX,ITOP
113 FORMAT(72H THIS PROGRAM LIMITS THE NUMBER OF DISCRETE STEPS OF THE
15 TATE VARIBLE TOI6,26H AND THIS PROBLEM REQUIRES 16)
2002 FORMAT(*)** ERROR HALT*)
2003 WRITE(6,2001)
2000 WRITE(6,2001)
2001 FORMAT(*1*,* END OF DATA FILE*)
5 TOP
END
CSEARCH DISCRETE FIBDNACCI SEARCH SUBROUTINE
                                                                                 END
                                                                              DISCRETE FIBONACCI SEARCH SUBROUTINE
SUBROUTINE SEARCH (AA, BB, DELYY, XX 40DE, YYBEST, BEST)
DIMENSION F(150)
   CSEARCH
                                                                SUBROUTINE SEARCH (AA, BB, DELYY, XXYODE, YYBEST, BEST)
DIME NSION F(150)

OPTIMIZE WITH RESPECT TO Y BETWEEN AA AND BB IN STEPS OF DELYY
STORE OPTIMUM Y IN YYBEST AND THE OPTIMUM VALUE OF THE OBJECTIVE
FUNCTION IN BEST
XMODE=1 FOR MAXIMIZE
XMODE=1 FOR MAXIMIZE
XMODE=1 FOR MINIMIZE
XMODE=1 TO SEPORE IT IS USED FOR A SEARCH

DELY=0ELY=0ELY=0ELY=1 TO SEARCH

A=AA
B=BB
XMODE=XXMODE
IF (1)=1.0

F(1)=1.0

F(2)=2.0

DO 1 F=3.150
F(1)=1.0

F(1)=1.0

F(1)=1.0

IF (F(1)-1.0E+35) 1,2,2

I I=1 FOR F(1) F(1) F(1) F(1) F(1) F(1) F(1)

F(2)=2.0

OO 1 F(3)=3.50
F(1)=1.0

F(3)=3.50
F(1)=1.0

F(1)=1.0

F(1)=1.0

F(2)=2.0

OO 1 F(3)=3.50
F(1)=1.0

F(1)
CCCCCCCC
                            100
                                                       2
                                                       1
                            101
                2002
```

```
IF(N-1; 102,102,103
103 IF((GY2-GY1;*XMODE) 19,19,20
19 YLD=Y1+DELY
        111 YYBEST=Y1
                           RETURN
YI=A
                          CALL FUNCTN(Y1,GY1)
Y2=B
CALL FUNCTN(Y2,GY2)
GO TO 102
Y1=A
CALL FUNCTN(Y1,GY1)
GO TO 111
CFUNCTN
SUBROUTINE FUNCTN(Y,GY)
DIMENSION FN(10001),FNM1(10001),DNOFXN(10001)
REAL * 8 TAB(4)
COMMON /CDN/TAB
COMMON /CDN/TAB
COMMON XN,N,DN,YN,RN,SLOW,XHIGH,DELX,DLOW,DHIGH,DELD,NUMBER
COMMON YLOW,YHIGH,DELY,NUFF,FN,JTDP,NNFLAG,NMAX,XLAM
COMMON YLOW,YHIGH,DELY,NUFF,FN,JTDP,NNFLAG,NMAX,XLAM
COMMON A,B,C,D,E,SUMELT,KODE
EQUIVALENCE (FN(1),FNM1(1),DNOFXN(1))
DN=Y
NOUTPE=6
CET TO 1 IN TRANFM TO INDICATE AN INFEASIBLE XM
                            NOUTPE=6
Jump may be set to 1 in tranfm to indicate an infeasible xn-1
     C JUMP MAY BE SET TO 1 IN TRANFM TO INDICATE AN INFEASIBLE XN-1

JUMP TO CALL TRANFM
CALL STGRET

X MODE = 1 FOR MIN, -1 FOR MAX

IF (JUMP.EQ.11RN=99999*XMODE

401 K=(YN-YLOW)/DELY+1.001

IF (K) 212.212.209

212 HRITE (NOUTPE.210) N.XN.DN.YN
210 FORMAT(///9H AT STAGE 15.9H WITH KN=E15.8,8H AND DN=E15.8,12H XN-1

1 EQUALS = 16.8,2 1 H AND IS OUT OF LIMITS///)

2002 FORMAT(*1**,* ERROR HALT*)

2003 WRITE (NOUTPE.2002)

2004 IF (K-JTOP) 205.206.212

2006 RNM1=FNM1(JTOP)

GO TO 207

X=YLOW+X*DELY

RNM1=FNM1(K)+(FNM1(K+1)-FNM1(K))*(YN-X)/DELY

207 GO TO (21,22,23,24).NNFLAG

ON=RN+RNM1

GO TO 137
```

FILE: DP4 FORTRAN AL NAVAL POSTGRADUATE SCHOOL

```
22 QN=RN*RNM1

GO TO 137

23 IF(RN-RNM1) 141.141.142

141 QN=RN

GO TO 137

142 QN=RNM1

GO TO 137

24 IF(RN-RNM1) 145.145.146

145 QN=RNM1

GO TO 137

146 QN=RNM

137 GY=QN

RETURN

END
```

FILE: STORE FORTRAN AL NAVAL POSTGRADUATE SCHOOL

```
CSTGRET

SUBROUTINE STGRET

OIMENSION FN(10001), FNMI(10001), ONOFXN(10001), A(101), B(101), C(101)

DIMENSION D(101), E(101)

REAL + B TAB(+)

COMMON XON, TAB

COMMON XON, TAB, YN, RN, SLOW, XHIGH, DELX, DLOW, DHIGH, DELD, NUMBER

COMMON A, B, C, D, E, SUMELT, KOD21, KOD22

EQUIVALENCE (FN(1), FNMI(1), DNOFXN(1))

ION=INT(DN)

ABA (N)+B(N)

IFIND - OINT(DN)

TEMP=0.

IF(1S.LT.O) GO TO 11

TEMM=EXP(-AB)

IF(1S.LT.O) GO TO 11

TEMP=TEMM

IF(1S.LT.O) GO TO 11

OIO 10 1=1:1S

TEMP=TEMM

IF(1S.LT.O) GO TO 11

O TO TEMP=TEMM

COINT INUE

COINT INUE

COINT INUE

SMA=(AB+10-TEMP)+(IDN-AB)+(1.-COF))/AB

RN=E(N)+AB+SYA/SUMELT

RETURN

40 THUS=(1-COF)+(AB+AB-2.+AB+ION+ION+(IDN+1))/(2.+A(N))

X+TEMP=B(N)+(AB-ION)/2.
                                      RETURN

40 TWUS = (1.-CDF) * (AB *AB - 2.* AB * I DN + I DN + (I DN + 1)) / (2.* A (N))

X + TEM P * B(N) * (AB - I DN) / 2.

I F (K OD E1. Eq. 3) GO TO 5 O

RN = E (N) * TWUS / SUME LT

RETURN

50 CONTINUE

AMSR T = TWUS / AB

AMTB F = 1. / A (N)

AMTT R = D(N)

RN = (AMTB F) / (AMTB F + AMTTR + AMSRT)

RETURN

77 RN = C(N) * DN

I F (K OD E2. Eq. 1. AND • N. E Q. 1. AND • YN. L T. XN ) RN = 999999

RETURN

END
                                                                  END
```

FILE: DLIMIT FORTRAN AL NAVAL POSTGRADUATE SCHOOL

```
COLIMIT

SUBROUTINE DLIMIT

DIMENSION FN(10001), FNM1(10001), DNOFXN(10001), A(101), B(101), C(101)

REAL * 8 TAB(4)

COMMON /CON/TAB

COMMON XN,N,DN,YN,RN, SLOW, XHIGH,DELX, DLOW,DHIGH,DELD, NUMBER

COMMON YLOW, YHIGH, DELY, NUFF, FN, JTOP, NNFLAG, NMAX, XLAM

COMMON A, B, C, O, E, SUMELT, KODE2, KODE2

EQUIVALENCE (FN(1), FNM1(1), DNOFXN(1))

IF(KODE2.NE.) IGO TO 37

DLOW=0.

DELD=1.

DHIGH=AMIN1(XN/C(N),50.)

RETURN

37 AB=A(N)*B(N)

TEMP=TERM

IF(IS.EQ.0) GO TO 11

DO 10 I=1,IS

TEMP=TEMP*AB/I

IF(IS.EQ.0) GO TO 11

TEMP=TEMP*AB/I

IF(IERM.GE.0)99999) GD TO 11
```

FILE: TRANFM FORTRAN AL NAVAL POSTGRADUATE SCHOOL

```
CTRANFM

SUBROUTINE TRANFM

DIMENSION FY(1000); FNM1(10001), ONDFX N(10001), A(101), B(101), C(101)

REAL * 8 TAB(*);
COMMON XN.N.D.YN.RN.SLDW.XHIGH.DELX.DLDW.DHIGH.DELD.NUMBER
COMMON XN.N.D.YN.RN.SLDW.XHIGH.DELX.DLDW.DHIGH.DELD.NUMBER
COMMON A.BIC.D.E.SUMELT.KGDE1, KJOE2
EQUIVALENCE [FN,1]; FNM1(1), ONOFXN(1);
IF(K DDE2.NE.0) GD TO 12

YN=XN-C(N)*DN

12 IDN=INTIDN)
AB=A(N)*B(N)
IS=1DN
IF(IS.LT.O) GD TO 11
IERM=0.
IF(IS.LT.O) GD TO 11
IERM=EXP(-AB)
IF(IS.LT.O) GD TO 11
IF(IS.LT.O) GD TO 15
SMA=(I.-TEMP)+(IDN-AB)*(I.-CDF)*AB
IF(VN.LT.O) YN=0.0
                              IF(N.NE.1.AND.YN.LT.O.OR.N.NE.1.AND.YN.GT.1.)JUMP=1
IF(N.EQ.1.AND.YN.GT.O.)JUMP=1
IF(JUMP.EQ.1)YN=O.
RETURN
S1 AMSRT=THUS/AB
AMTHF=1./A(N)
AMTTR=0(N)
ANTTR=0(N)
AV=(AMTBF)/(AMTBF+AMTTR+AMSRT)
YN=XN/AV
AV IS AVAIL
RETURN
50 YN=XN-E(N)*THUS/SUMELT
IF(YN.LE.O.)YN=O.
RETURN
END
                                                          IF(YN.LT.O) YN=0.0
         C
```

```
DIMENSION A(20), B(20), C(20], D(2), E(20), MINQ(20)
DIMENSION T(10,30), F(1200), DX(10,1200), TN(10,31)
INTEGER BUDGET, BB, BBP1, DX
REAL * B TIME, CTIME
INDA TA = 8
NOUT PE = 6
READ (INDATA, 888) NMAX, BUDGET

888 FORMAT(215)
READ (INDATA, 777) (MINQ(I), I=1, VMAX)
777 FORMAT(2015)
DO 333 K=1, NMAX
READ (INDATA, 999) A(K), C(K), E(K), B(K), D(K)
999 FORMAT (5F10, 4)
WRITE(NGUTPE, 999) A(K), B(K), C(K), D(K), E(K)
333 CONTINUE
TIME=CTIME(1)
SUMELT=0.
DO 30 I=1, NMAX
30 SUMELT=SUMELT+E(I) * A(I) * 8(I)
      DO 10 I=1,NMAX

DX(I,1)=0

DO 110 KP1=1,31

K=KP1-1

AB=A(I)*B(I)

TERM=EXP(-AB)

TEMP=TERM

IF(K.EQ.O) GD TO 11

DO 14 JI=1.K

TEMP=TEMP*AB/JI

IF(TERM.GE...999999) GO TO 11

IF(TEMP.EE...0000001) GO TO 11

14 TERM=TERM +TEMP
   40 TWUS=(1.-CDF)*(AB*AB-2.*AB*K+K*(K+1))/(2.*A(I))
X+TEMP*B(I)*(AB-K)/2.
110 TN(I,KP1)=E(I)*TWUS/SUMELT
DO 70 K=1.30
70 T(I,K)=TN(I,K+1)-TN(I,K)
10 CONTINUE
DO 456 IJK=1,10
456 WRITE(6,555)(TN(KI,IJK),KI=1,NMAX)
555 FORMAT(5F12.7)
        DD 80 I=1,NMAX

LIM=30/MINQ(I)

D0 85 K=1,LIM

TMOD=0.

MM=MING(I)

D0 90 J=1,MM

90 IMOD=TMOD+T(I,(K-1)+MINQ(I)+J)

T(I,K)=TMOD

85 CONTINUE

C(I)=MINQ(I)+C(I)

80 CONTINUE
                        I 8D=BUDGET+1
DO 100 BBP1=1,IBD
BB=BBP1-1
XMIN=0.
ISTAR=0
TRY=0.
DO 210 I=1,NMAX
IF(BB-C(I).LT.0) GO TO 210
IF(BB-C(I).GT.0) GO TO 211
TRY=AMINI(TRY,T(I.1))
GO TO 212
```

FORTRAN AL NAVAL POSTGRADUATE SCHOOL

FILE: RECMOD

FILE: RECMOD FORTRAN AL NAVAL POSTGRADUATE SCHOOL

```
211 TRY=T(I.DX(I.BBP1-C(I))+1)+F(BBP1-C(I))
212 IF (TRY.GT.XMIN) GO TO 210
    XMIN=TRY
    ISTAR=1
210 CONTINUE
    F(BBP1)=XMIN
```

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